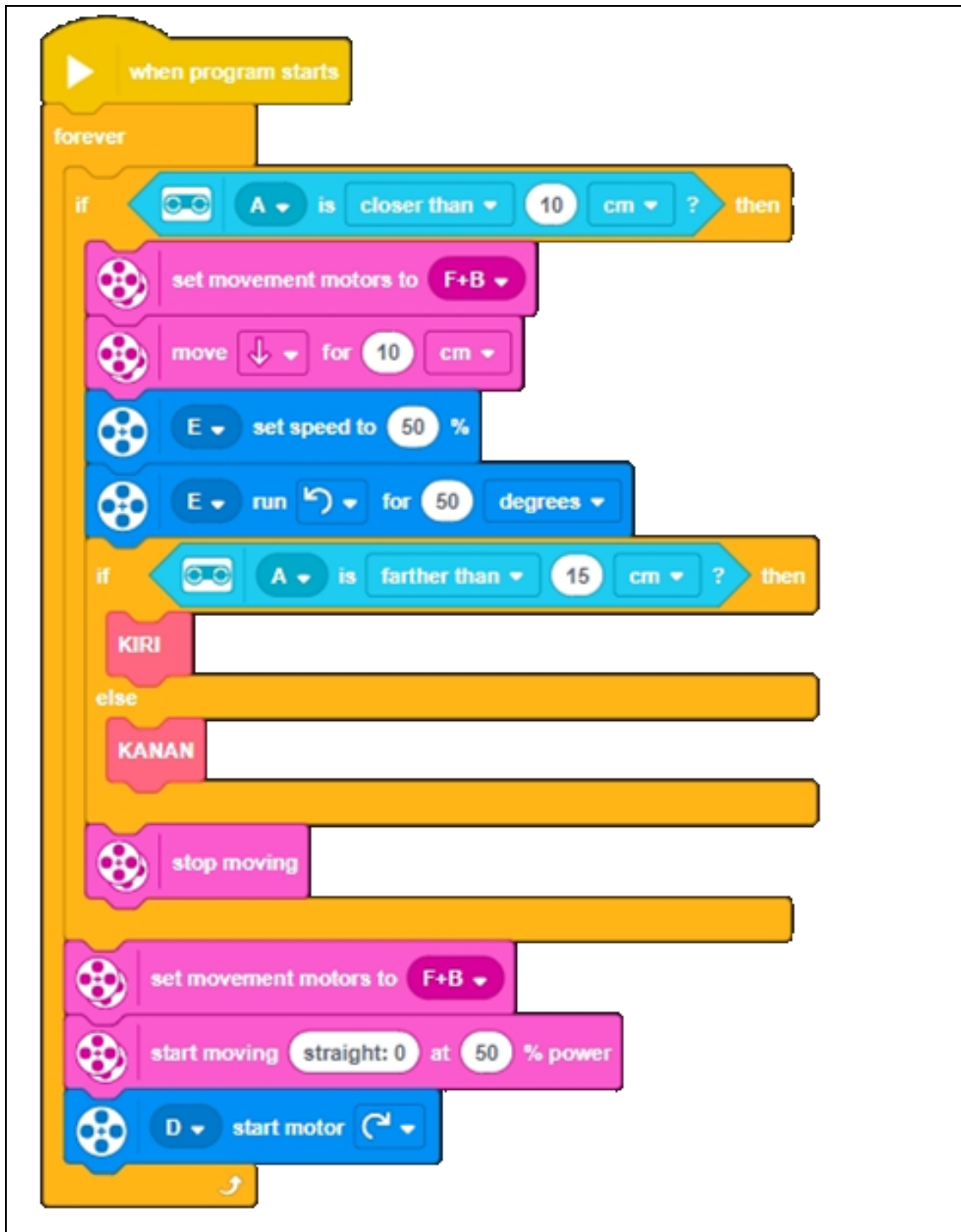


Listing Program



```
define KIRI
  E run for 50 degrees
  E run for 50 degrees
  E run for 50 degrees
  set movement motors to F+B
  start moving left: -100
  set yaw angle to 0
  wait until is yaw angle in between -90 and -89 ?
  stop moving

define KANAN
  E run for 50 degrees
  E run for 50 degrees
  E run for 50 degrees
  set movement motors to F+B
  start moving right: 100
  set yaw angle to 0
  wait until is yaw angle in between 89 and 90 ?
  stop moving
```