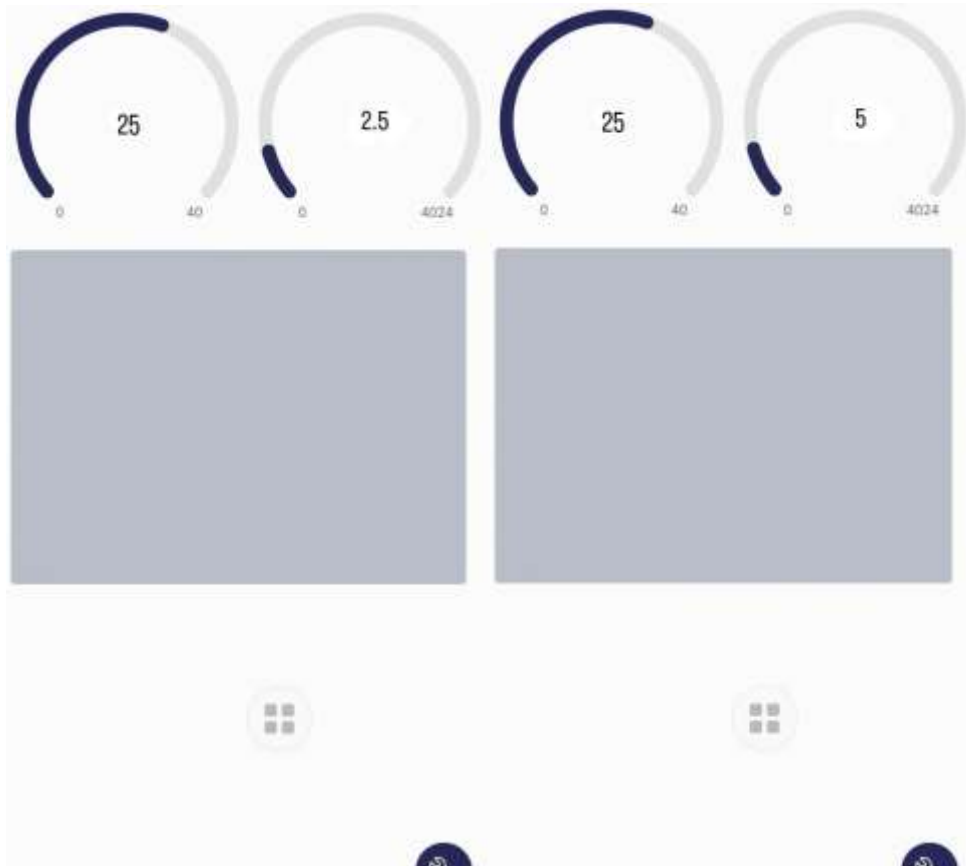
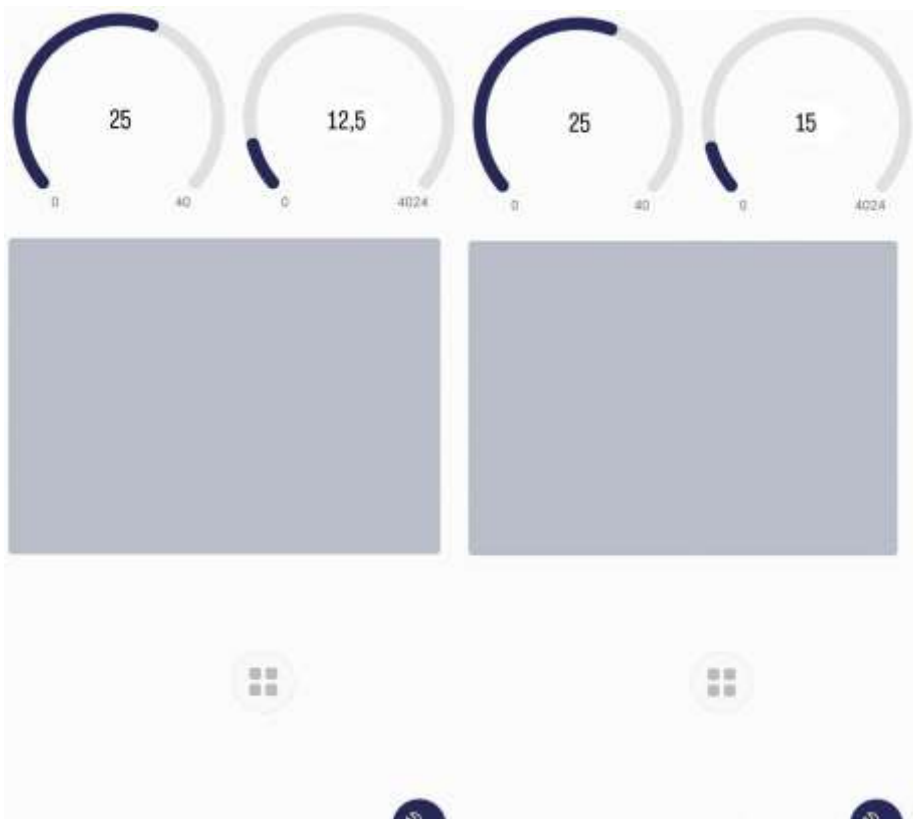
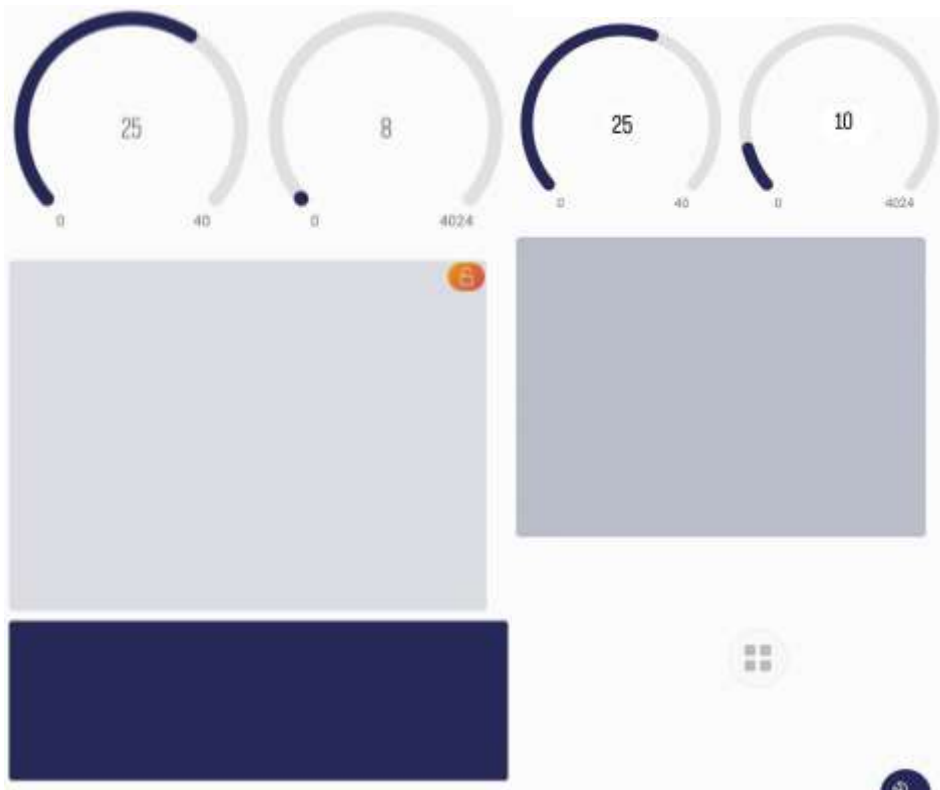
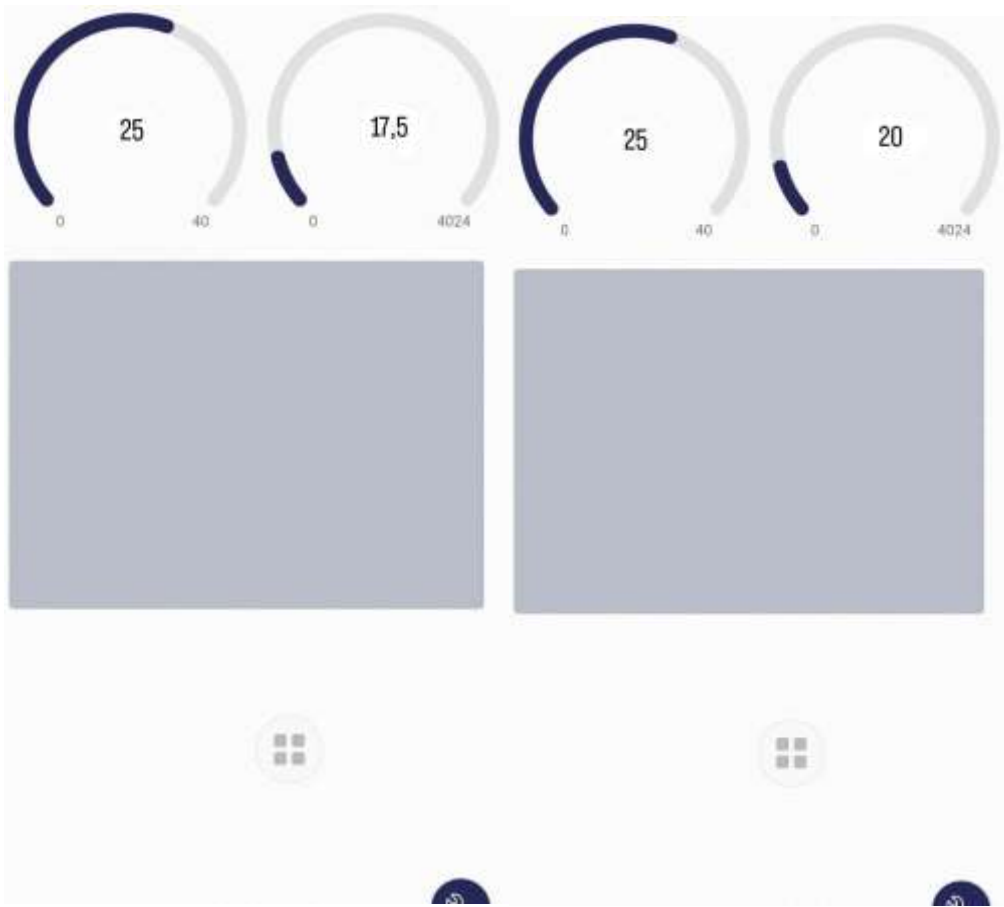


LAMPIRAN

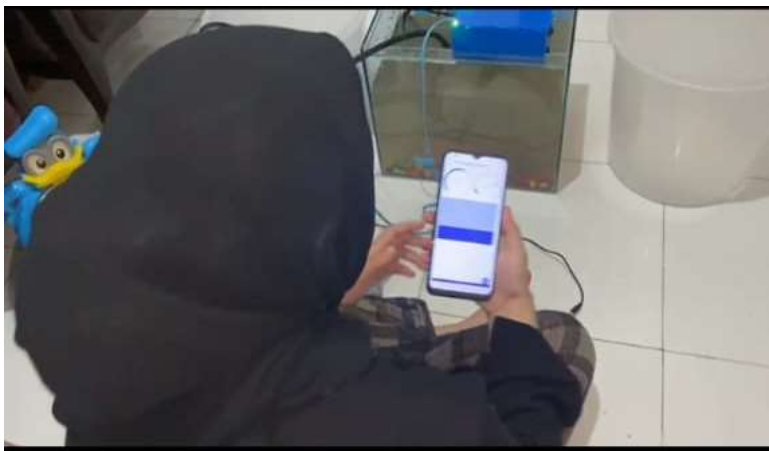
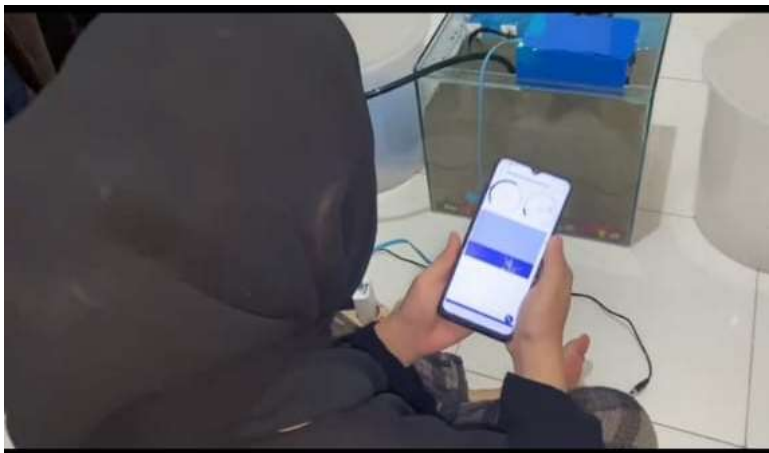








DOKUMENTASI



Tampilan Codingan “Rancang Bangun Sistem Monitoring Kekeruhan Air pada Akuarium Otomatis Berbasis Internet Of Things”

```
#define BLYNK_TEMPLATE_ID "TMPL6UysO_oi-"
#define BLYNK_TEMPLATE_NAME "Nessa Putri Salsabila"
#define BLYNK_AUTH_TOKEN "BA8rROvmmPoL1IOYVce7b-mOia1QB6ZK"
#define BLYNK_PRINT Serial

#include <WiFi.h>
#include <WiFiClient.h>
#include <BlynkSimpleEsp32.h>

// You should get Auth Token in the Blynk App.
// Go to the Project Settings (nut icon).
char auth[] = BLYNK_AUTH_TOKEN;

// Your WiFi credentials.
// Set password to "" for open networks.
char ssid[] = "vivo"; //nama hotspot yang digunakan
char pass[] = "12345678";

int teg;
int kekeruhan;
#include <OneWire.h>

#include <DallasTemperature.h>

#define ONE_WIRE_BUS 32

OneWire oneWire(ONE_WIRE_BUS);
```

```
DallasTemperature sensorSuhu(&oneWire);

int nilai_suhu;

//===== HCSR =====
int trigPin = 12;
int echoPin = 13;
long duration, cm;

int pompa2 =14; //isi
int pompa1=27 ; //buang
WidgetLCD layar(V3);
void setup() {
  Serial.begin(115200);
  Blynk.begin(auth, ssid, pass);
  Blynk.begin(auth, ssid, pass, "blynk.cloud", 80);
//===== HCSR04 =====
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  pinMode(pompa1, OUTPUT);
  pinMode(pompa2, OUTPUT);
  digitalWrite(pompa1,HIGH);
  digitalWrite(pompa2,HIGH);
}

void loop() {
  Blynk.run();
  bacaHCSRde();
  nilai_suhu=baca_suhu();
```

```

int val=analogRead(33);
teg=val*(5.0/1024);
kekeruhan=100.00+(teg/4.16)*100.00;
int kek=map(kekeruhan,0,1024,0,25);
  Blynk.virtualWrite(V1, kek);
  Blynk.virtualWrite(V2, 152+nilai_suhu);
  // Blynk.virtualWrite(V4, kekeruhan);
  delay(250);
  //Serial.println();
  // layar.clear();
  // layar.print(0,0, "Monitoring Kekeruhan ");
  // layar.print(0,1, "Pompa OFF");
  // delay(300);
  //Serial.print(150+nilai_suhu);
  // Serial.println("Celcius");
  // bacaHCSRde();

  //364
  if (kekeruhan>1){
    // while(1){
      digitalWrite(pompa2,LOW);
      digitalWrite(pompa1,LOW);
      layar.clear();
      layar.print(0,0, "Medeteksi ");
      layar.print(0,1, "kekeruhan Air");
      Blynk.logEvent("Deteksi Kekeruhan");
      // break;
    //}
  }
  else if (kekeruhan<1){

```



```

digitalWrite(pompa2,HIGH);
digitalWrite(pompa1,HIGH);
layar.clear();
layar.print(0,0,"Tidak Medeteksi ");
layar.print(0,1,"Kekeruhan Air");
}
}

```

```

void bacaHCSRde() {
digitalWrite(trigPin, LOW);
delayMicroseconds(5);
digitalWrite(trigPin, HIGH);
delayMicroseconds(5);
digitalWrite(trigPin, LOW);
pinMode(echoPin, INPUT);
duration = pulseIn(echoPin, HIGH);
cm = (duration / 2) / 29.1;
Serial.print(cm);
// Serial.println("cm");
Blynk.virtualWrite(V0, 20-cm);
if (cm>20){
Blynk.logEvent("AIR PENUH");
//digitalWrite(pompa2,HIGH);
}

delay(250);
}

```

```

float baca_suhu(){

```

```
sensorSuhu.requestTemperatures();

float suhu = sensorSuhu.getTempCByIndex(0);

return suhu;}

BLYNK_WRITE(V1)
{
  int pinValue1 = param.asInt();
  if (pinValue1 == 1)
  {
    //digitalWrite(pompa1,LOW);

    layar.clear();
    layar.print(0,0,"FILL OUT");
    layar.print(0,1,"POMPA 1 ON");
    delay(300);
    digitalWrite(pompa2,LOW);

    //delay(5000);
    //digitalWrite(pompa1,HIGH);

    //break;
  }
}

BLYNK_WRITE(V2)
{
  int pinValue2 = param.asInt();// assigning incoming value from pin V1 to a variable
```

```
if (pinValue2 == 1)
{
  //while(1){
  // digitalWrite(pompa2,LOW);
  //delay(5000);
  // digitalWrite(pompa1,HIGH);
  digitalWrite(pompa2,HIGH);
  layar.clear();
  layar.print(0,0,"Monitoring ");
  layar.print(0,1,"Kekeruhan Air");
  delay(300);

  //break;
  //}
}
}
```



```
BLYNK_WRITE(V3)
{
  int pinValue3 = param.asInt();
  if (pinValue3 == 1)
  {
    // digitalWrite(pompa1,LOW);
    layar.clear();
    layar.print(0,0,"FILL OUT");
    layar.print(0,1,"POMPA 2 ON");
    delay(300);
    digitalWrite(pompa1,LOW);
    //delay(5000);
    //digitalWrite(pompa1,HIGH);
```

```
    //break;
  //}

}
}
BLYNK_WRITE(V10)
{
  int pinValue2 = param.asInt(); // assigning incoming value from pin V1 to a variable
  if (pinValue2 == 1)
  {
    //while(1){
    // digitalWrite(pompa2,LOW);
    //delay(5000);
    // digitalWrite(pompa1,HIGH);
    digitalWrite(pompa1,HIGH);
    layar.clear();
    layar.print(0,0,"Monitoring ");
    layar.print(0,1,"Kekeruhan Air");
    delay(300);
    //break;
  //}
}
}
```