

LAMPIRAN

CURICULUM VITAE

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RIWAYAT PENDIDIKAN

PENDIDIKAN	NAMA SEKOLAH	TAHUN LULUS
SD	SDN 07 KIKIM SELATAN	2013
SMP	SMPN 38 PALEMBANG	2016
SMA	SMA BINA WARGA 1 PALEMBANG	2019

PENGALAMAN INTERNSHIP:

NO	PENGALAMAN	TAHUN
1	INTERNSHIP PT. ANGKASA PURA II	2022

PENGALAMAN ORGANISASI

NO	PENGALAMAN	TAHUN
1	ANGGOTA TIM ROBOT POLSRI	2019
2	ANGGOTA LDK KHARISMA POLSRI	2019

Semua data yang tercantum dalam Curriculum Vitae ini adalah benar dan dapat dipertanggung jawabkan.

Palembang, Agustus 2023

(Rahmika)

RINCIAN BIAYA

No	Komponen	Harga Satuan	Kuantitas
1	Motor Elektrik (AC)	Rp. 3.500.000	1 Buah
2	NodeMCU	Rp. 45.000	1 Buah
3	Modul Relay 4ch	Rp. 35.000	1 Buah
4	Power Supply	Rp. 150.000	1 Buah
5	Switch	Rp. 100.000	2 Buah
6	Rel dan Baut	Rp. 120.000	2 buah
7	Plat Besi	Rp. 70.000	1 buah
8	Ubec	Rp. 45.000	1 Buah
9	Mini Breadboard	Rp. 10.000	1 Buah
10	Jumper	Rp. 10.000	1 Buah
11	Box	Rp. 25.000	1 Buah
12	Kabel	Rp. 100.000	2 Buah
13	Total	Rp. 4.210.000	

KODE PROGRAM PERANGKAT KERAS

```
#include <Arduino.h>
#if defined(ESP32) || defined(ARDUINO_RASPBERRY_PI_PICO_W)
#include <WiFi.h>
#elif defined(ESP8266)
#include <ESP8266WiFi.h>
#endif

#define PIN_RELAY_1  D2 // the Arduino pin, which connects to
the IN1 pin of relay module
#define PIN_RELAY_2  D3 // the Arduino pin, which connects to
the IN2 pin of relay module
#define PIN_RELAY_3  D4 // the Arduino pin, which connects to
the IN3 pin of relay module
#define PIN_RELAY_4  D5 // the Arduino pin, which connects to
the IN4 pin of relay module

#include <Firebase_ESP_Client.h>

// Provide the token generation process info.
#include <addons/TokenHelper.h>

// Provide the RTDB payload printing info and other helper
functions.
#include <addons/RTDBHelper.h>

/* 1. Define the WiFi credentials */
#define WIFI_SSID "OPPO A15s"
#define WIFI_PASSWORD "mikamika"

// For the following credentials, see
examples/Authentications/SignInAsUser/EmailPassword/EmailPassw
ord.ino

/* 2. Define the API Key */
#define API_KEY "AIzaSyBOynK_pfrKQzRiFEJJD5L0wG9n95CaPGc"

/* 3. Define the RTDB URL */
#define DATABASE_URL "smart-gate-m-default-
rtdb.firebaseio.com" //<databaseName>.firebaseio.com or
<databaseName>.<region>.firebaseio.com

/* 4. Define the user Email and password that already
registerd or added in your project */
#define USER_EMAIL "rhmaprlaa1542@gmail.com"
#define USER_PASSWORD "niyuroh15"

// Define Firebase Data object
//FirebaseData fbdo;
```



```

FirebaseData stream;
FirebaseData fbdo;

FirebaseAuth auth;
FirebaseConfig config;

unsigned long sendDataPrevMillis = 0;

unsigned long count = 0;

#ifdef ARDUINO_RASPBERRY_PI_PICO_W
WiFiMulti multi;
#endif

volatile bool dataChanged = false;
String data_didapat = "";

const int shiftAmount = 15; // Number of positions to shift
each character

String decrypt(String message, int shift) {
    String decryptedText = "";

    for (int i = 0; i < message.length(); i++) {
        char c = message.charAt(i);

        // Check if the character is a letter
        if (isAlpha(c)) {
            // Get the ASCII value of the character
            int asciiValue = c;

            // Shift the ASCII value back by the specified amount
            int shiftedAsciiValue = (asciiValue - 'A' - shift + 26)
% 26 + 'A';

            // Convert the shifted ASCII value back to a character
            char decryptedChar = shiftedAsciiValue;

            // Append the decrypted character to the result
            decryptedText += decryptedChar;
        } else {
            // If the character is not a letter, append it as it is
            decryptedText += c;
        }
    }

    return decryptedText;
}

void streamCallback(FirebaseStream data)
{

```

```

    Serial.printf("stream path, %s\n", event path, %s\n", data type,
%s\n", event type, %s\n",
                data.streamPath().c_str(),
                data.dataPath().c_str(),
                data.dataType().c_str(),
                data.eventType().c_str());
    printResult(data); // see addons/RTDBHelper.h
    data_didapat = data.to<String>();
    Serial.println();

    // This is the size of stream payload received (current and
    max value)
    // Max payload size is the payload size under the stream
    path since the stream connected
    // and read once and will not update until stream
    reconnection takes place.
    // This max value will be zero as no payload received in
    case of ESP8266 which
    // BearSSL reserved Rx buffer size is less than the actual
    stream payload.
    Serial.printf("Received stream payload size: %d (Max.
%d)\n", data.payloadLength(), data.maxPayloadLength());

    // Due to limited of stack memory, do not perform any task
    that used large memory here especially starting connect to
    server.
    // Just set this flag and check it status later.
    dataChanged = true;
}

void streamTimeoutCallback(bool timeout)
{
    if (timeout)
        Serial.println("stream timed out, resuming...\n");

    if (!stream.httpConnected())
        Serial.printf("error code: %d, reason: %s\n",
stream.httpCode(), stream.errorReason().c_str());
}

void setup()
{
    Serial.begin(115200);

#ifdef ARDUINO_RASPBERRY_PI_PICO_W
    multi.addAP(WIFI_SSID, WIFI_PASSWORD);
    multi.run();
#else
    WiFi.begin(WIFI_SSID, WIFI_PASSWORD);
#endif

    Serial.print("Connecting to Wi-Fi");
    unsigned long ms = millis();

```

```

while (WiFi.status() != WL_CONNECTED)
{
  Serial.print(".");
  delay(300);
#if defined(ARDUINO_RASPBERRY_PI_PICO_W)
  if (millis() - ms > 10000)
    break;
#endif
}
Serial.println();
Serial.print("Connected with IP: ");
Serial.println(WiFi.localIP());
Serial.println();

Serial.printf("Firebase Client v%s\n\n",
FIREBASE_CLIENT_VERSION);

/* Assign the api key (required) */
config.api_key = API_KEY;

/* Assign the user sign in credentials */
auth.user.email = USER_EMAIL;
auth.user.password = USER_PASSWORD;

/* Assign the RTDB URL (required) */
config.database_url = DATABASE_URL;

/* Assign the callback function for the long running token
generation task */
config.token_status_callback = tokenStatusCallback; // see
addons/TokenHelper.h

// Or use legacy authenticate method
// config.database_url = DATABASE_URL;
// config.signer.tokens.legacy_token = "<database secret>";

// To connect without auth in Test Mode, see
Authentications/TestMode/TestMode.ino

////////////////////////////////////
////////////////////////////////////
// Please make sure the device free Heap is not lower than
80 k for ESP32 and 10 k for ESP8266,
// otherwise the SSL connection will fail.

////////////////////////////////////
////////////////////////////////////

#if defined(ESP8266)
// In ESP8266 required for BearSSL rx/tx buffer for large
data handle, increase Rx size as needed.

```

```

    fbdo.setBSSLBufferSize(2048 /* Rx buffer size in bytes from
512 - 16384 */, 2048 /* Tx buffer size in bytes from 512 -
16384 */);
#endif

    // Limit the size of response payload to be collected in
FirebaseData
    fbdo.setResponseSize(2048);

    Firebase.begin(&config, &auth);

    // The WiFi credentials are required for Pico W
    // due to it does not have reconnect feature.
#if defined(ARDUINO_RASPBERRY_PI_PICO_W)
    config.wifi.clearAP();
    config.wifi.addAP(WIFI_SSID, WIFI_PASSWORD);
#endif

    // Comment or pass false value when WiFi reconnection will
control by your code or third party library
    Firebase.reconnectWiFi(true);

    // Recommend for ESP8266 stream, adjust the buffer size to
match your stream data size
#if defined(ESP8266)
    stream.setBSSLBufferSize(2048 /* Rx in bytes, 512 - 16384
*/, 512 /* Tx in bytes, 512 - 16384 */);
#endif

    if (!Firebase.RTDB.beginStream(&stream, "/message"))
        Serial.printf("stream begin error, %s\n\n",
stream.errorReason().c_str());

    Firebase.RTDB.setStreamCallback(&stream, streamCallback,
streamTimeoutCallback);

    Firebase.setDoubleDigits(5);

    config.timeout.serverResponse = 10 * 1000;

    /** Timeout options.

        //WiFi reconnect timeout (interval) in ms (10 sec - 5 min)
when WiFi disconnected.
        config.timeout.wifiReconnect = 10 * 1000;

        //Socket connection and SSL handshake timeout in ms (1 sec
- 1 min).
        config.timeout.socketConnection = 10 * 1000;

        //Server response read timeout in ms (1 sec - 1 min).
        config.timeout.serverResponse = 10 * 1000;

```

```

    //RTDB Stream keep-alive timeout in ms (20 sec - 2 min)
    when no server's keep-alive event data received.
    config.timeout.rtdbKeepAlive = 45 * 1000;

    //RTDB Stream reconnect timeout (interval) in ms (1 sec -
    1 min) when RTDB Stream closed and want to resume.
    config.timeout.rtdbStreamReconnect = 1 * 1000;

    //RTDB Stream error notification timeout (interval) in ms
    (3 sec - 30 sec). It determines how often the readStream
    //will return false (error) when it called repeatedly in
    loop.
    config.timeout.rtdbStreamError = 3 * 1000;

    Note:
    The function that starting the new TCP session i.e. first
    time server connection or previous session was closed, the
    function won't exit until the
    time of config.timeout.socketConnection.

    You can also set the TCP data sending retry with
    config.tcp_data_sending_retry = 1;

```

```
*/
```

```

// initialize digital pin as an output.
pinMode(PIN_RELAY_1, OUTPUT);
pinMode(PIN_RELAY_2, OUTPUT);
pinMode(PIN_RELAY_3, OUTPUT);
pinMode(PIN_RELAY_4, OUTPUT);

digitalWrite(PIN_RELAY_1, HIGH);
digitalWrite(PIN_RELAY_2, HIGH);
digitalWrite(PIN_RELAY_3, HIGH);
digitalWrite(PIN_RELAY_4, HIGH);
}

void loop()
{

#ifdef ARDUINO_RASPBERRY_PI_PICO_W
    Firebase.RTDB.runStream();
#endif

// if (Firebase.ready() && (millis() - sendDataPrevMillis >
15000 || sendDataPrevMillis == 0))
// {
//     sendDataPrevMillis = millis();
//     count++;
//     FirebaseJson json;
//     json.add("data", "hello");
//     json.add("num", count);

```

```

//      Serial.printf("Set json... %s\n\n",
Firebase.RTDB.setJSON(&fbdo, "/test/stream/data/json", &json)
? "ok" : fbdo.errorReason().c_str());
//  }

    if (dataChanged)
    {
        dataChanged = false;
        Serial.println(decrypt(data_didapat,shiftAmount));

        if (decrypt(data_didapat,shiftAmount) == "BUKA") {
            Serial.println("pintu dibuka");
            digitalWrite(PIN_RELAY_1, LOW);
            delay(1000);
            digitalWrite(PIN_RELAY_1, HIGH);
        } else {
            Serial.println("pintu ditutup");
            digitalWrite(PIN_RELAY_2, LOW);
            delay(1000);
            digitalWrite(PIN_RELAY_2, HIGH);
        }

        //      Serial.println("ada perubahan data");

        // When stream data is available, do anything here...
    }
}

// Firebase.ready() should be called repeatedly to handle
authentication tasks.

//  if (Firebase.ready() && (millis() - sendDataPrevMillis >
15000 || sendDataPrevMillis == 0))
//  {
//      sendDataPrevMillis = millis();
//      Serial.printf("Set bool... %s\n",
Firebase.RTDB.setBool(&fbdo, F("/test/bool"), count % 2 == 0)
? "ok" : fbdo.errorReason().c_str());
//      Serial.printf("Get bool... %s\n",
Firebase.RTDB.getBool(&fbdo, FPSTR("/test/bool")) ?
fbdo.to<bool>() ? "true" : "false" :
fbdo.errorReason().c_str());
//      bool bVal;
//      Serial.printf("Get bool ref... %s\n",
Firebase.RTDB.getBool(&fbdo, F("/test/bool"), &bVal) ? bVal ?
"true" : "false" : fbdo.errorReason().c_str());
//      Serial.printf("Set int... %s\n",
Firebase.RTDB.setInt(&fbdo, F("/test/int"), count) ? "ok" :
fbdo.errorReason().c_str());
//

```

```

//      Serial.printf("Get int... %s\n",
Firebase.RTDB.getInt(&fbdo, F("/test/int")) ?
String(fbdo.to<int>()).c_str() : fbdo.errorReason().c_str());
//
//      int iVal = 0;
//      Serial.printf("Get int ref... %s\n",
Firebase.RTDB.getInt(&fbdo, F("/test/int"), &iVal) ?
String(iVal).c_str() : fbdo.errorReason().c_str());
//
//      Serial.printf("Set float... %s\n",
Firebase.RTDB.setFloat(&fbdo, F("/test/float"), count + 10.2)
? "ok" : fbdo.errorReason().c_str());
//
//      Serial.printf("Get float... %s\n",
Firebase.RTDB.getFloat(&fbdo, F("/test/float")) ?
String(fbdo.to<float>()).c_str() :
fbdo.errorReason().c_str());
//
//      Serial.printf("Set double... %s\n",
Firebase.RTDB.setDouble(&fbdo, F("/test/double"), count +
35.517549723765) ? "ok" : fbdo.errorReason().c_str());
//
//      Serial.printf("Get double... %s\n",
Firebase.RTDB.getDouble(&fbdo, F("/test/double")) ?
String(fbdo.to<double>()).c_str() :
fbdo.errorReason().c_str());
//
//      Serial.printf("Set string... %s\n",
Firebase.RTDB.setString(&fbdo, F("/test/string"), F("Hello
World!")) ? "ok" : fbdo.errorReason().c_str());
//
//      Serial.printf("Get string... %s\n",
Firebase.RTDB.getString(&fbdo, F("/test/string")) ?
fbdo.to<const char *>() : fbdo.errorReason().c_str());
//
//      // For the usage of FirebaseJson, see
examples/FirebaseJson/BasicUsage/Create_Edit_Parse.ino
//      FirebaseJson json;
//
//      if (count == 0)
//      {
//          json.set("value/round/" + String(count), F("cool!"));
//          json.set(F("value/ts/.sv"), F("timestamp"));
//          Serial.printf("Set json... %s\n",
Firebase.RTDB.set(&fbdo, F("/test/json"), &json) ? "ok" :
fbdo.errorReason().c_str());
//      }
//      else
//      {
//          json.add(String(count), F("smart!"));
//          Serial.printf("Update node... %s\n",
Firebase.RTDB.updateNode(&fbdo, F("/test/json/value/round"),
&json) ? "ok" : fbdo.errorReason().c_str());
//      }

```

```

//
//   Serial.println();
//
//   // For generic set/get functions.
//
//   // For generic set, use Firebase.RTDB.set(&fbdo, <path>,
<any variable or value>)
//
//   // For generic get, use Firebase.RTDB.get(&fbdo,
<path>).
//   // And check its type with fbdo.dataType() or
fbdo.dataTypeEnum() and
//   // cast the value from it e.g. fbdo.to<int>(),
fbdo.to<std::string>().
//
//   // The function, fbdo.dataType() returns types String
e.g. string, boolean,
//   // int, float, double, json, array, blob, file and null.
//
//   // The function, fbdo.dataTypeEnum() returns type enum
(number) e.g. fb_esp_rtdb_data_type_null (1),
//   // fb_esp_rtdb_data_type_integer,
fb_esp_rtdb_data_type_float, fb_esp_rtdb_data_type_double,
//   // fb_esp_rtdb_data_type_boolean,
fb_esp_rtdb_data_type_string, fb_esp_rtdb_data_type_json,
//   // fb_esp_rtdb_data_type_array,
fb_esp_rtdb_data_type_blob, and fb_esp_rtdb_data_type_file
(10)
//
//   count++;
// }
//}

```

/ NOTE:**

When you trying to get boolean, integer and floating point number using getXXX from string, json and array that stored on the database, the value will not set (unchanged) in the FirebaseData object because of the request and data response type are mismatched.

There is no error reported in this case, until you set this option to true
config.rtdb.data_type_stricted = true;

In the case of unknown type of data to be retrieved, please use generic get function and cast its value to desired type like this

```

Firebase.RTDB.get(&fbdo, "/path/to/node");

float value = fbdo.to<float>();
String str = fbdo.to<String>();

```



```
*/  
  
/// PLEASE AVOID THIS ////  
  
// Please avoid the following inappropriate and inefficient  
use cases  
/**  
  
    1. Call get repeatedly inside the loop without the  
appropriate timing for execution provided e.g. millis() or  
conditional checking,  
    where delay should be avoided.  
  
    Everytime get was called, the request header need to be  
sent to server which its size depends on the authentication  
method used,  
    and costs your data usage.  
  
    Please use stream function instead for this use case.  
  
    2. Using the single FirebaseData object to call different  
type functions as above example without the appropriate  
    timing for execution provided in the loop i.e., repeatedly  
switching call between get and set functions.  
  
    In addition to costs the data usage, the delay will be  
involved as the session needs to be closed and opened too  
often  
    due to the HTTP method (GET, PUT, POST, PATCH and DELETE)  
was changed in the incoming request.  
  
    Please reduce the use of swithing calls by store the  
multiple values to the JSON object and store it once on the  
database.  
  
    Or calling continuously "set" or "setAsync" functions  
without "get" called in between, and calling get continuously  
without set  
    called in between.  
  
    If you needed to call arbitrary "get" and "set" based on  
condition or event, use another FirebaseData object to avoid  
the session  
    closing and reopening.  
  
    3. Use of delay or hidden delay or blocking operation to  
wait for hardware ready in the third party sensor libraries,  
together with stream functions e.g. Firebase.RTDB.readStream  
and fbdo.streamAvailable in the loop.  
  
    Please use non-blocking mode of sensor libraries (if  
available) or use millis instead of delay in your code.
```

4. Blocking the token generation process.

Let the authentication token generation to run without blocking, the following code *MUST BE AVOIDED*.

```
while (!Firebase.ready()) <---- Don't do this in while loop
{
    delay(1000);
}
*/
```

KODE PROGRAM PERANGKAT LUNAK (APLIKASI)

1. Tampilan Menu Pertama

```
<?xml version="1.0" encoding="utf-8"?>
<LinearLayout
xmlns:android="http://schemas.android.com/apk/res/android"
xmlns:app="http://schemas.android.com/apk/res-auto"
xmlns:tools="http://schemas.android.com/tools"
android:layout_width="match_parent"
android:layout_height="match_parent"
android:layout_gravity="center"
android:background="@color/teal_700"
android:gravity="center"
android:orientation="vertical"
tools:context=".MainActivity">

<LinearLayout
    android:layout_width="match_parent"
    android:layout_height="wrap_content"
    android:gravity="center"
    android:orientation="horizontal">

    <TextView
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:layout_marginBottom="20dp"
        android:fontFamily="sans-serif-black"
        android:text="SMART GATE REMOTE"
        android:textColor="#FFFFFF"
        android:textSize="30sp"
        app:layout_constraintBottom_toBottomOf="parent"
        app:layout_constraintEnd_toEndOf="parent"
        app:layout_constraintStart_toStartOf="parent"
        app:layout_constraintTop_toTopOf="parent" />
</LinearLayout>

<LinearLayout
    android:layout_width="350dp"
    android:layout_height="350dp"
    android:gravity="center"
    android:orientation="horizontal">

    <ImageView
        android:id="@+id/imageView"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        app:srcCompat="@drawable/gate" />
</LinearLayout>

<LinearLayout
```

```

        android:layout_width="120dp"
        android:layout_height="100dp"
        android:layout_marginTop="20dp"
        android:orientation="horizontal">

        <Button
            android:id="@+id/btnMasuk"
            android:layout_width="200dp"
            android:layout_height="wrap_content"
            android:layout_weight="1"
            android:backgroundTint="@color/white"
            android:text="ENTER"
            android:textColor="@color/teal_700"
            android:textSize="24sp"
            app:iconPadding="6dp" />
    </LinearLayout>

</LinearLayout>

```

2. Tampilan Menu Kedua

```

<?xml version="1.0" encoding="utf-8"?>
<LinearLayout
    xmlns:android="http://schemas.android.com/apk/res/android"
    xmlns:app="http://schemas.android.com/apk/res-auto"
    xmlns:tools="http://schemas.android.com/tools"
    android:layout_width="match_parent"
    android:layout_height="match_parent"
    android:background="@color/teal_700"
    android:orientation="vertical"
    android:gravity="center"
    android:layout_gravity="center"
    tools:context=".button">

    <ImageView
        android:id="@+id/imageView2"
        android:layout_width="300dp"
        android:layout_height="300dp"
        android:foregroundGravity="center"
        app:srcCompat="@drawable/ic_launcher_foreground"
        tools:layout_editor_absoluteX="55dp"
        tools:layout_editor_absoluteY="34dp" />

    <Button
        android:id="@+id/buttonOpen"
        android:layout_width="wrap_content"
        android:layout_height="wrap_content"
        android:backgroundTint="@color/white"
        android:foregroundGravity="center"
        android:gravity="center"
        android:text="OPEN"
        android:textColor="@color/teal_700"
        android:textSize="36sp"

```

```
tools:layout_editor_absoluteX="136dp"
tools:layout_editor_absoluteY="274dp" />

<Button
    android:id="@+id/buttonClose"
    android:layout_width="wrap_content"
    android:layout_height="wrap_content"
    android:backgroundTint="@color/white"
    android:gravity="center"
    android:text="CLOSE"
    android:textColor="@color/teal_700"
    android:textSize="34sp"
    tools:layout_editor_absoluteX="131dp"
    tools:layout_editor_absoluteY="397dp" />

<Button
    android:id="@+id/buttonStop"
    android:layout_width="wrap_content"
    android:layout_height="wrap_content"
    android:backgroundTint="@color/white"
    android:foregroundGravity="center"
    android:gravity="center"
    android:text="STOP"
    android:textColor="@color/teal_700"
    android:textSize="36sp"
    tools:layout_editor_absoluteX="136dp"
    tools:layout_editor_absoluteY="274dp" />
</LinearLayout>
```

KODE PROGRAM PENGOLAHAN DATA

```
package com.mikacyuuu.smartgatem;

import androidx.appcompat.app.AppCompatActivity;
import android.content.Intent;
import android.os.Bundle;
import android.view.View;
import android.widget.Button;
import com.google.firebase.database.DatabaseReference;
import com.google.firebase.database.FirebaseDatabase;

public class MainActivity extends AppCompatActivity {

    Button btnMasuk;
    @Override
    protected void onCreate(Bundle savedInstanceState) {
        super.onCreate(savedInstanceState);
        setContentView(R.layout.activity_main);
        btnMasuk = findViewById(R.id.btnMasuk);
        btnMasuk.setOnClickListener(new View.OnClickListener()
        {
            @Override
            public void onClick(View view) {
                Intent intent = new
                Intent(MainActivity.this,button.class);
                startActivity(intent);
            }
        });
    }
}
```

```
package com.mikacyuuu.smartgatem;

import androidx.appcompat.app.AppCompatActivity;
import android.content.Intent;
import android.os.Bundle;
import android.view.View;
import android.widget.Button;

import com.google.firebase.database.DatabaseReference;
import com.google.firebase.database.FirebaseDatabase;

public class button extends AppCompatActivity {

    Button buttonOpen,buttonClose,buttonStop;
    @Override
    protected void onCreate(Bundle savedInstanceState) {
        super.onCreate(savedInstanceState);
        setContentView(R.layout.activity_button);

        FirebaseDatabase database =
        FirebaseDatabase.getInstance();
```

```

        DatabaseReference myRef =
database.getReference("message");

        buttonOpen = findViewById(R.id.buttonOpen);
        buttonClose = findViewById(R.id.buttonClose);
        buttonStop = findViewById(R.id.buttonStop);
        buttonOpen.setOnClickListener(new
View.OnClickListener() {
            @Override
            public void onClick(View view) {

//                Intent intent = new Intent(button.this,);
                myRef.setValue(encrypt("buka",15));
            }
        });
        buttonStop.setOnClickListener(new
View.OnClickListener() {
            @Override
            public void onClick(View view) {
//                Intent intent = new Intent(button.this,);
                myRef.setValue(encrypt("tutup",15));
            }
        });
        buttonStop.setOnClickListener(new
View.OnClickListener() {
            @Override
            public void onClick(View view) {
                myRef.setValue(encrypt("stop",15));
            }
        });
    }
    public static String encrypt(String message, int shift) {
        StringBuilder encryptedText = new StringBuilder();

        for (int i = 0; i < message.length(); i++) {
            char c = message.charAt(i);

            // Check if the character is a letter
            if (Character.isLetter(c)) {
                // Convert the character to uppercase
                c = Character.toUpperCase(c);

                // Shift the character by the specified amount
                c = (char) ((c - 'A' + shift) % 26 + 'A');
            }

            encryptedText.append(c);
        }

        return encryptedText.toString();
    }
}

```



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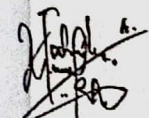
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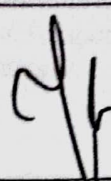
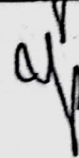
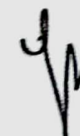







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NIP. 197105282006042001

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Mahasiswa tersebut telah memenuhi persyaratan dan dapat mengikuti Ujian Tugas Akhir (TA) pada Tahun Akademik 2023/2024

Palembang, Agustus 2023

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Innovation in Smart Fencing with Internet of Things (IoT) Technology for Ease of Use

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The fence is a structure that is deliberately designed to limit or protect the house. The fence is made high and equipped with a safety lock to protect the home so only the owner can enter. The fence serves to provide protection and lock views so that the house becomes safer. It is usually opened manually by hand to open and close the fence. This method is considered very inconvenient and time-consuming. This research underlies the idea of creating an automatic fence opening and closing system using a smartphone by utilizing the Internet of Things (IoT) technology in order to facilitate the work to open and close the fence, as well as reduce the effort and time required when opening and closing the fence when manually driven. A smartphone is used as a microcontroller contained in the ESP8266 WiFi module via an internet connection to connect to the Android application. To move the fence using an electric motor as the driving force which is connected directly to the microcontroller. When the fence opens and closes, the relay will activate and activate to give orders to the electric motor to move the fence. The fence will stop when the switch opens. When the switch close responds, the motor will stop moving. Time data results are stored in Firebase and the results of the design are expected that all components are connected properly so that automatic fences can be used. This research is expected to make a valuable contribution to the development of science and improve the quality of life of the community by using advanced technology that responds to the need for more intuitive and efficient access to fences.

Keywords: Electric Motor, Electric Fences, Internet of Things, NodeMCU.

I. INTRODUCTION

The fence is the main part of a house in terms of security. The fence is an element part of the design of a house that is important for its existence[1]. The fence has a function as a barrier or safety designed to limit or prevent movement across the boundary it makes [2]. Fences are usually made of an access point by opening the gate by pushing it to the right or left[3]. The fence used is a sliding fence that moves and runs on rails with wheels mounted on the bottom of the fence. To open and close the fence must be done by moving the door by hand, however, if a vehicle such as a car wants to go out and enter the house you have to get off the vehicle first, and if under certain conditions such as rain opening and closing the gate of the house, it will be very troublesome and time-consuming. This problem underlies the idea of making the gate open and close automatically using a remote and smartphone (android) by utilizing Internet of Things (IoT) technology. Where the system used contains an

arrangement of infrastructure that is integrated with each other so that it can make human work more effective and efficient, the Internet of Things (IoT) runs by utilizing the use of smart devices and internet networks.

The Internet of Things (IoT) is a network of physical objects. The internet is not just a network of computers but has developed into a network of devices of all types and sizes, vehicles, smartphones, household appliances, toys, cameras, medical equipment and industrial systems, animals, people, buildings, everything connected, everything communicating & information sharing based on established protocols to achieve intelligent reorganization, positioning, browsing, security, control, and even personal real-time online monitoring, online upgrade, process control, and administration[4]. The importance of the Internet of Things can be seen by its increasing application in various lines of life today. IoT gives us many ideas to participate in various aspects of development from micro to macro around the world [5]. IoT must be able to provide information about environmental conditions and control electronic devices in real time, therefore using Firebase as a database capable of sending data in real time [6].

In an increasingly connected world and as technology evolves, gates are becoming more than just physical boundaries that separate spaces [7]. The need for secure, fast and convenient access is increasing, driving innovations in the form of smart fence innovations with IoT technology for user convenience. The sophistication of Internet of Things (IoT) technology offers an exciting and effective way to address these challenges. The combination of connected hardware and intelligent software allows the fence to interact with its environment and respond to user needs in real-time. This means that users can control their gate with ease, whether they are nearby or not.

By addressing existing problems, this research also brings a new concept to the world of fence access, providing a more practical, faster and safer solution. By applying this technology, the innovation relies on technical sophistication. It ensures that the user experience remains easy to access, even for those with a deep technical background.

The results of this research not only reflect a new technological solution but set our sights on a more connected future. This innovation contributes not only to our understanding of how technology can play an important role in providing real solutions but also to our

Understanding of how technology can be used to improve lives.

Based on researchers' research of automatic gate systems [8], this system uses RF 315 wireless remote control. This system has a weakness, namely the use of remote control is very limited. If the homeowner leaves the remote control behind, the homeowner cannot enter the house.

Researchers [9] researched automatic garage door control systems. This system uses RFID indicators and microcontroller based alarms. The weakness of this system is that the RFID tag is unreadable or has an error, the garage door cannot be opened.

Meanwhile, based on research [10] on an automatic control system using digital image processing of vehicle license plates. This control system also has drawbacks, namely the vehicle license plate detection sensor can only be used with a maximum distance of 20

The Smart Fence Innovation with IoT Technology for User Convenience presents several novelties and advantages that distinguish it from other research in this field. This innovation is designed with a focus on user convenience, the use of Internet of Things (IoT) technology, which shows that the fence is not just a static barrier, but is actively connected to the surrounding environment and can respond to various situations, the use of remote access which allows users to control the fence remotely via smartphone which provides advantages in terms of convenience. In the era of ever-evolving technology, innovation continues to be the main driver to meet society's demands for convenience and efficiency. In this context, this research aims to realize a significant step forward by developing "Smart Fence Innovation with IoT Technology for User Convenience". Combining revolutionary Internet of Things (IoT) technologies with the need for easy access, this research presents a solution that stands out by providing a more intuitive and responsive door access experience. In this production, we will explore the novelty and key benefits of this innovation and illustrate how this research significantly contributes to the development of science and the welfare of society through the use of advanced technology.

Based on these studies, the authors designed an automatic fence control system based on the Internet of Things (IoT) with the aim of facilitating human work in opening and closing fences and protecting homeowners to remain safe when opening and looking at the fence at night or when bad weather. This study aims to design automatic fences using IoT technology by answering the research question of whether automatic fences can be designed based on IoT. The research analysis is that fences can be designed and used using IoT technology based on smartphones. This system uses NodeMCU as a controller for the gate. NodeMCU Esp8266, is an IoT device or wifi module that can be integrated with devices controlled and monitored via the internet network [11]-[12]. An electric motor as the drive for the gate, and

an Android smartphone as a device that orders the fence to open or close directly connected to the internet. All devices are connected using the internet with the Android Studio application.

II. METHODOLOGY

A. Research Stages

The following section presents the architecture of the Internet of Things (IoT) Based Automatic Fence Control research. How to design the entire system can be seen in the image below.

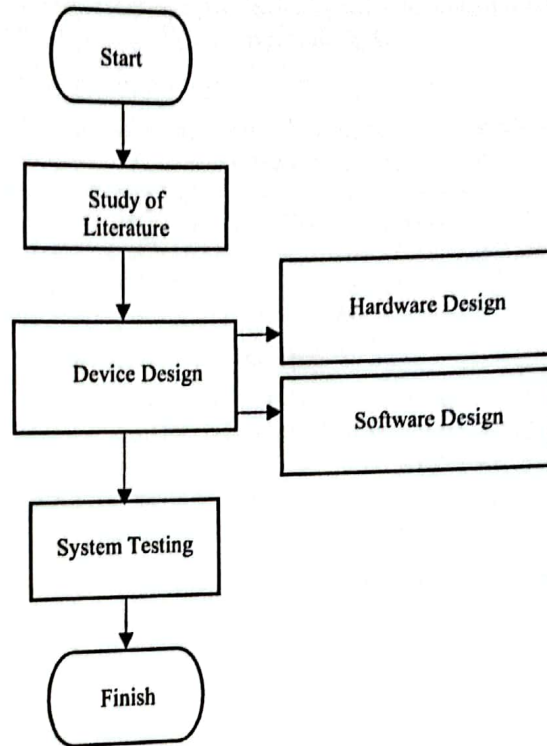


Figure 1. Research Architecture Diagram of Automatic Fence Control System

Figure 1 is the overall flowchart of the research methodology step framework for Internet of Things (IoT) Based Automatic Fence Design. In this research, a literature study was carried out by collecting and taking references from various sources such as books, theses, journals, and the internet, where these sources will become a reference for this research.

Hardware design is the process of designing all components until they are all connected to the fence. The hardware design starts with creating a schematic. The NodeMCU, which uses the ESP8266 WiFi module, is connected to a 24-volt power supply as the power source. The 4-channel relay module helps control the opening and closing of the fence when it receives commands from the NodeMCU. The relay will activate when it receives a command, so the motor driver will rotate and move the fence to open and close. The electric motor used is an AC-type electric motor because this type of motor is stronger to move the large weight of the fence. The motor driver

stop moving when the open switch and close switch are pressed, where the switch functions to disconnect the movement of the motor wheel, then the motor driver will be stationary. The fence will automatically be stationary. The software design can be seen in the picture below in Figure 3.

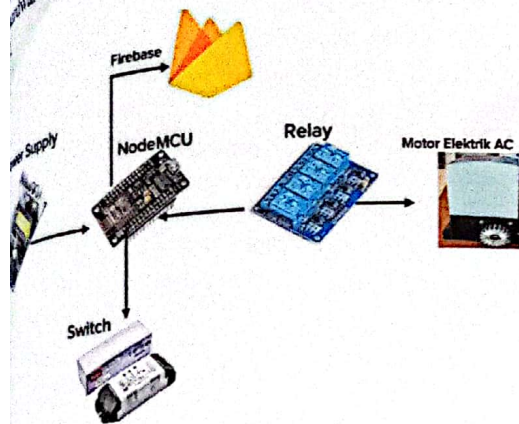


Figure 2. Hardware Design

Table 1. Hardware Component Specifications

Component Name	Description
Motor Elektrik AC	a. Power AC b. Motor Speed 1400rpm c. Max Gate Weight 1000kg d. Gate Speed 12m/min e. Temperature -20°C - 55°C f. Protecting Class IP44
NodeMCU	NodeMCU ESP8266
Power Supply	Power Supply 24V
Relay	Modul Relay 4 Channel
Switch	Switch Open & Close

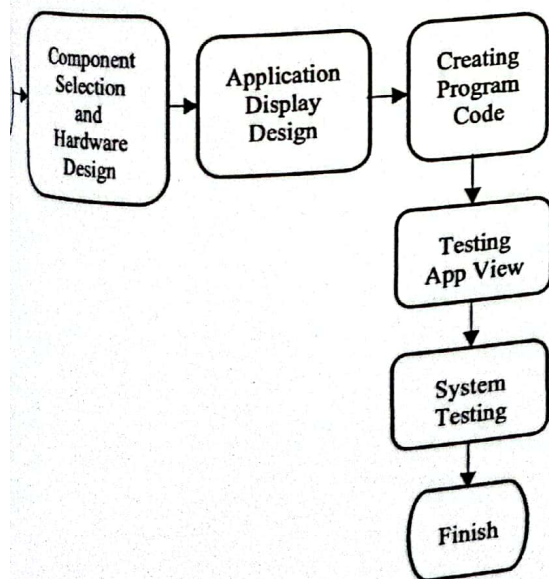


Figure 3. Automatic Fence Control Software Design

Figure 3 is a framework that will be executed in software design that aims to produce a fence control application design. The stages include:

a. Component selection and hardware design

The first step is to select the components that will be used for the hardware design. These components include a 24V power supply, NodeMCU ESP8266, 4-channel relay module, AC electric motor, open switch, and close switch.

a. Application display design

The application display design aims to make the application display design easier to make. In designing the application is designed using Android Studio.

b. Create program code

The hardware program code is created on the Arduino IDE using the C++ programming language, and the application program code is created in Android Studio using C++ and Java. The hardware program code is connected through Firebase as a data processor, and the data is sent to NodeMCU. NodeMCU reads the sent data and gives incoming commands at the same time.

c. Test the appearance of the application

Testing the application display is to test each option that is available with the features that have been designed then, the application is successful if all the features that have been designed are used successfully.

d. System testing

This section includes system testing related to tools and applications that have been designed and successfully tested.

System testing in this design includes application testing, which aims to see if application commands can operate the fence. Testing the electric motor wheel movement function to see if it works as expected. Distance and network speed testing aim to see how the fence speeds up at different distances and network speeds. Finally, see the results of power consumption used in testing the system. System testing first made a flowchart to describe the program's course against the system. The picture below is a flowchart process in testing the system to be made. The first step is to start and initialize any tools or components used. If the fence is open, the motor will move until the open switch command responds (yes), and the motor will stop automatically. The motor will move if the fence is closed until the Close switch command (yes) responds. Then, the motor will stop, and the fence will close. If the open or closed switch does not respond, the fence open/close command is repeated. The flowchart is shown in Figure 3.

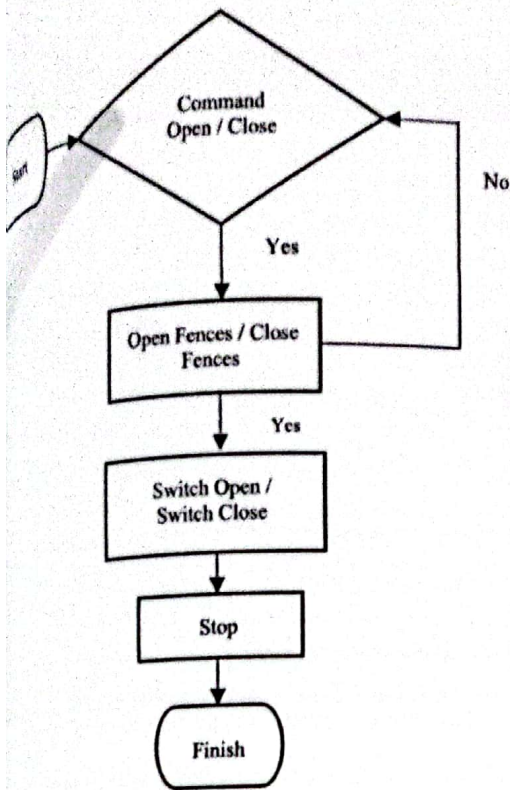


Figure 4. Complete System Experiment Flowchart

In this test, the component will be placed near the fence, where it will be tested in its entirety by the automatic opening and closing test. Then several variables are measured which included voltage, current, electric motor speed, and the electric power used. As well as the duration and time needed by the fence when opening and closing. Test data will be stored in real-time in Firebase using the Arduino Caesar Chiper method (random writing method) which is confidential so that incoming data is not known to other people.

III. RESULTS AND DISCUSSION

The results of this research are based on components assembled and programmed based on the Internet of Things (IoT) using smartphones with applications made in the Android Studio. In this design, using a type of iron gate sliding, this fence weighs about 500 kg with a length of 5.25 meters. This tool was designed as a set of components consisting of a 24-volt power supply as a power source for the device, NodeMCU as a component that is connected by the application using the ESP8266 module and instructs the device. Nodemcu is connected to Firebase to execute commands in the application. The relay is turned on when it receives a command to move the electric motor. The type of relay used is a 4-channel relay module. The electric motor used is an AC motor that can move the fence with a maximum weight of 1000 kg at a motor speed of 1400 rpm. AC electric motors are used because the fence to be installed weighs approximately 500 kg, so it is safe and avoids overloading the motor. When the motor is moving, the relay performs its function to disconnect or stop the movement of the motor wheel when the fence is in

motion. Figure 5 and Figure 6 below are the research results when the fence opens and closes.



Figure 5. Fence in Open State



Figure 6. Fence in Closed State

A. Hardware Program Code Section

The program code section in Figure 7 is a hardware interface program that uses the Arduino IDE.

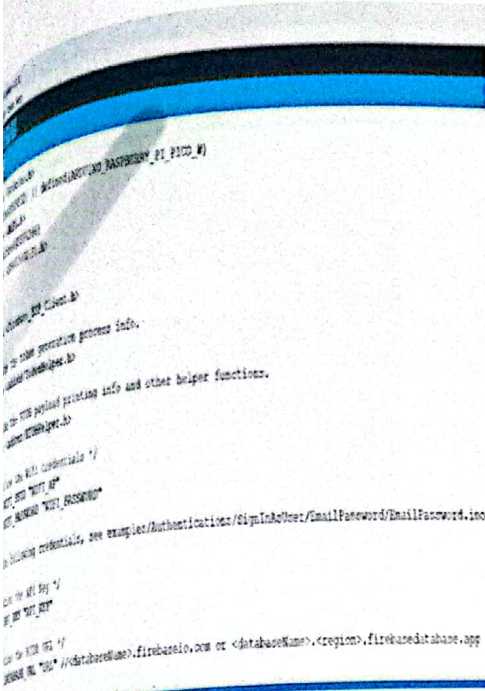


Figure 7. Hardware Program Code on Arduino IDE

Figure 7 NodeMCU is programmed in C++ using WiFi and WiFi Password to connect to the internet. The data will be managed using Firebase which is programmed on the Arduino IDE, then the data will be read in real-time.

1. Application Programming Code in Android Studio

This section is a program component created to design the appearance of the application to make it easier to control the tool to be tested. The application display page is designed in Android Studio with a view menu whose buttons have their respective functions. The application display program code uses the C++ and Java programming languages.

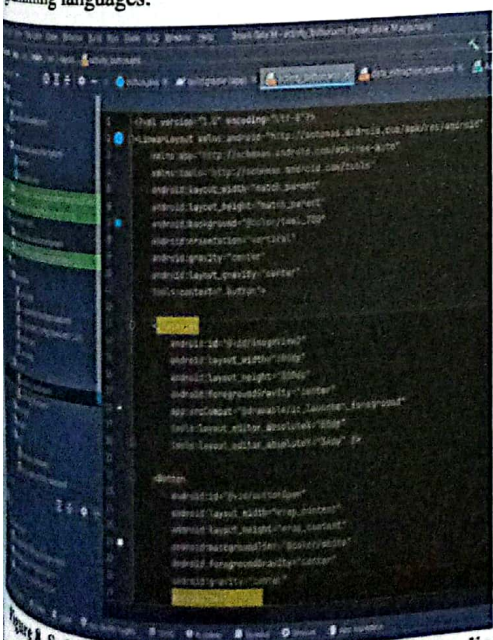


Figure 8. Software Design Program Code in Android Studio

In Figure 8 several program codes are entered for the application display design in the form of open menus and closed menus. <LinearLayout which is for creating a layout for the element to be used. <ImageView is the program code when adding image elements to the application view you created. <Button is the program code on a pushable element or button element.

C. Application Display Page Results

In this section are the results of the design program for making automatic fence control applications. The design is made with a menu page that can be used for fence controllers to open and close, data obtained in real-time will be entered in Firebase. Applications that have been designed will be transferred to smartphones that are directly connected to the internet network. The display menu on the application installed on the smartphone can be used based on the features and functions that have been made. Smartphone (android) must be connected to the internet when running the system. The commands on the internet cannot be executed if the application is not connected to the internet. Suppose the internet is experiencing bad signal interference due to weather. In that case, the possibility is to wait for the internet to reconnect or the state of the internet in a stable connection. The picture below is the result of displaying the designed application. The difference between the two is the location of the application designed in Android Studio, and then its use is moved into the smartphone as a controller. Both have the same menu because the results of displaying the application on the smartphone are the results of designing in Android Studio, which is then moved into the smartphone.

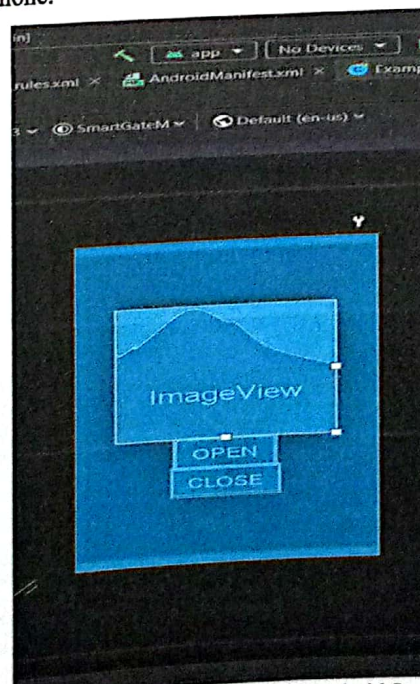


Figure 9. Application Menu in Android Studio

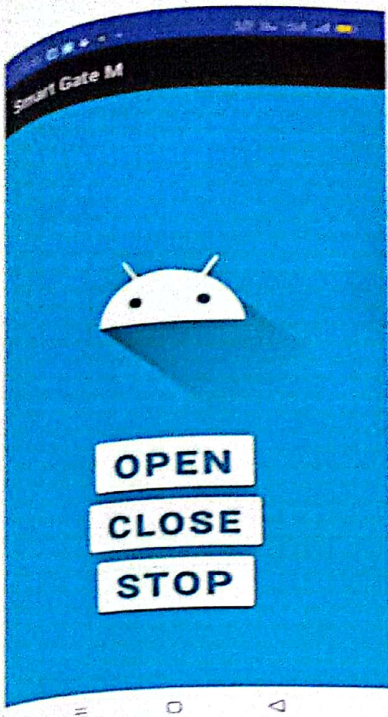


Figure 10. Application Menu on Smartphone

Figure 9 is the display result in Android Studio with image elements and buttons that have been designed with elements in Android Studio. Figure 10 is the display result of the application on a smartphone which has been tested for each feature based on its function before being implemented on the fence. The results of testing the application function can be seen in Table 1 below.

Table 2. Application Testing Results

Command	Required Time (Second)	Results Description
Open	23,74	Succeed
Close	23,67	Succeed
Stop	0	Succeed

Based on Table 1 the results of application testing were successful with different time descriptions. To open, moving the fence takes 23.74 seconds until the fence stops moving. Meanwhile, to close, moving the fence requires less time than opening it, which is 23.67 seconds. The fence immediately stops moving and stays still for 0 seconds. The fence immediately stops moving and stays still for 0 seconds. The test of the application function is successfully executed on each command, which then allows you to control the fence, use the application on a smartphone (Android) using an Internet connection. At the time of testing, the Internet connection was stable, did not experience any interference or was stable, the test was performed as intended. If the Internet connection is interrupted or not connected, what happens is you have to wait for the Internet to reconnect to the commands to run the fence control.

D. System Testing Results

In this section, data is the result of testing the Internet of Things (IoT) Based Automatic Fence Control System, where the system being tested is the performance of the tool that has been designed, the results of the fence control distance test using a smartphone connected to an internet connection, as well as the results of electricity consumption used on when testing the system. Incoming data will be sent to Firebase with the letter randomization method.

Table 3. Electric Motor Test Result

Wheel Movement	Wheel Spin	Result Description
Onward	Spin Forward	Corresponding
Back Off	Spinning Back	Corresponding
Stop	Not Moving	Corresponding

Table 2 is the result of the electric motor drive function test. Based on Table 2 the movement of the electric motor is successful according to its function, where when the wheel is forward the wheel rotates forward, while when the wheel is backward the wheel rotates backward, when the wheel stops moving the wheel will stop and stop moving.

Table 4. Test Fence Controller Distance with Network Speed

Range	Network Speed	Fence Speed	Description
1 Meter	2,00 Kbps	Normal	Succeed
2 Meter	0,30 Kbps	Normal	Succeed
3 Meter	0,26 Kbps	Normal	Succeed

Table 3 shows that the fence control distance test was successfully performed at different network speeds. The relationship between distance and kbps (kilobits per second) can affect system performance and responsiveness when testing automated Internet-connected fences. While physical distance may not have a direct impact on kbps speed, there are ways in which distance can interact with Internet connection performance in this context, namely signal quality. Whereas the distance between the device and the wireless access point increases, the wireless signal quality may decrease. Poor signal quality can result in a decrease in kbps speed and even dropouts. The Auto-Fence system response may also be affected if the connection becomes unstable. The speed of the gate has no effect at short or

...ences. Network speed in a fast or slow signal state ... cause the gate speed to change. The network ... is very low because the application does not ... much Internet network. To see the network ... it was recorded on the smartphone (Android) used ... the system.

Table 5. Result of Electricity Consumption

Fence Condition	Voltage (Volt)	Current (Ampere)	Power (Watt)
Normal	211	0	0
Open	211	3,4	717,4
Open 1/2	211	3,0	633
Open 1/4	211	3,3	696,3
Close	211	7,8	1645,8
Close 1/2	211	7,8	1645,8
Close 1/4	211	7,4	1561,4

Figure 4 shows the power consumption used during the test. The source voltage is 211 volts, measured with a multimeter, and the current output differs. The current used to open the fence is lower than the current used to close the fence, in this case, because the weight of the fence is heavier when the command is to close than when it is to open. The power consumption is from 633 to 1645 watts depending on the output current and voltage of the source. Power calculation is based on the principle of Ohm's law [13], where the formula is as follows:

$$P = V \times I \quad (1)$$

where: P = Power (watt)

V = Voltage (volt)

I = Current (ampere)

... voltage results do not change, and the current results ... because the electric motor used in this design is an ... type electric motor. AC type electric motor is an ... motor that is driven by alternating current or ... (AC), where AC voltage is a voltage

whose result is the same as the current, which is always changing and alternating [14].

Incoming data will be immediately sent to Firebase in real time. For data security, use the Arduino caesar cipher method (random letter method) so that if the incoming data is unknown or confidential. The results of the data sent can be seen in Figure 11 and Figure 12.

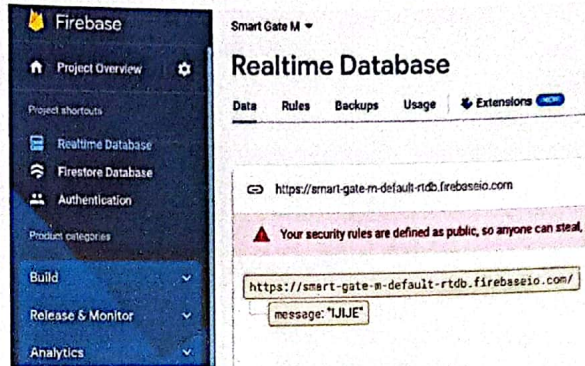


Figure 11. Result Data "Open"

Figure 11 is the result of the data when the fence moves open with the message: "IJJE". Commands are entered through the application by pressing the open button then the motor moves the fence and real-time data results are sent to Firebase.

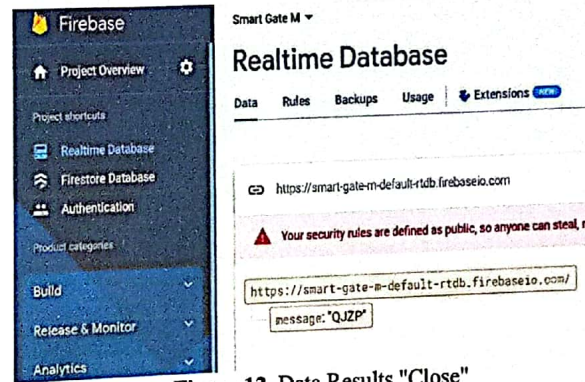


Figure 12. Data Results "Close"

Figure 12 is the result of the data when the fence moves closed with a message: "QJZP". Commands are entered through the application by pressing the close Button then an electric motor moves the fence and real-time data results are sent to firebase.

IV. CONCLUSION

In this design, it has successfully developed an automatic fence control system using Internet of Things (IoT) technology, with the advantage of being able to open the fence via a smartphone (android), which can be controlled remotely without having to push with your hands and walk towards the fence manually. Based on the results of the design and testing of an Internet of Things (IoT)-based automatic fence control system, it can be concluded that various components can be used properly and work according to their functions. The results of the data tested as a whole are appropriate and successful. The movement of the fence either opens, closes, or stops

...ing to the expected test. The electric motor moves
 fence, the wheels rotate forward when the wheel
 moves forward, the wheels rotate backward when the
 moves backward, and the wheels will automatically
 when the electric motor moves stop. By using the
 opening and closing the automatic gate can
 using an application installed on a smartphone that
 connected to an internet connection. Applications that
 designed according to and successfully tested each
 are that is in the application display. Testing the
 of the controller with an internet connection does
 change the movement of the fence. Move the fence
 normally from a distance of 1 meter or 3 meters.
 ing testing uses electric power consumption ranging
 633-1645 watts. With a source voltage of 211 volts
 opening current of 3.0-3.4 amperes, and a closing
 of 7.4-7.8 amperes. We hope that the results of our
 can be useful as well as learning. In future
 it is expected to be able to develop an Internet of
 (IoT)-based automatic fence control system that
 developed with a variety of other methods and is
 according to its function.

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