

## **LISTING PROGRAM**

```
#include <iostream>
#include <cstdlib>
#include <string>
#include <sys/types.h>
#include <dirent.h>
#include <errno.h>
#include <signal.h>
#include <unistd.h>
#include <csdarg>
#include <sys/time.h>
#include <opencv2/highgui/highgui.hpp>
#include "defs.h"
#include "FaceDetector.h"
#include "PersonRecognizer.h"
#include "VideoFaceDetector.h"
#include <pigpio.h>
#include <pigpiod_if.h>
#include "i2c.h"
#include "lcd.h"
#define I2C_FILE_NAME "/dev/i2c-1"
#define I2C_SLAVE_ADDR 0x3f
const cv::String CASCADE_FILE("haarcascade_frontalface_default.xml");
using namespace std;
using namespace cv;
#define GPIO_SERVO_OUT 5
const int GPIO_KEYPAD_NUM[4][2] = {
    {6, 11},
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    {13, 16},
    {19, 20},
    {26, 21}
};

const char KEYPAD_CHAR_MAP[16] = {
// //col 1
//  '*', '7', '4', '1',
//
// //col 2
//  '0', '8', '5', '2',
//
// //col 3
//  '#', '9', '6', '3',
//
// //col 4
//  'D', 'C', 'B', 'A'

//col 1
'A', 'B', 'C', 'D',

//col 2
'3', '6', '9', '#',

//col 3
'2', '5', '8', '0',

//col 4
'1', '4', '7', '*'
};
```

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/* password file */
#define PASSWORD_FILE "password.conf"

    //col
    gpioSetMode(GPIO_KEYPAD_NUM[i][1], PI_INPUT);
    gpioSetPullUpDown(GPIO_KEYPAD_NUM[i][1], PI_PUD_UP);
/* make a row out low, others as input */
void keypad_clear_row(int row_id) {
    int i;
    for (i = 0; i < 4; i++) {
        if (i == row_id) {
            gpioSetMode(GPIO_KEYPAD_NUM[i][0], PI_OUTPUT);
            gpioWrite(GPIO_KEYPAD_NUM[i][0], PI_LOW);
        } else {
            gpioSetMode(GPIO_KEYPAD_NUM[i][0], PI_INPUT);
            gpioSetPullUpDown(GPIO_KEYPAD_NUM[i][0], PI_PUD_OFF);
        }
    }
}

/* try for max 5 times */
for (i = 0; i < 5; i++) {
    printf("Verification #%d\n", i + 1);

    is_valid = id_lcd_buff = 0;
    memset lcd_buff, 0, sizeof (lcd_buff));

    /* get the password */
    for (;;) {
        /* get keypad data */

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dt_kpd = keypad_get_data();

/* continue on no keypressed */
if (dt_kpd == 0xff) {
    continue;
}

/* valid? */
/* number */
tmp_kpd = KEYPAD_CHAR_MAP[dt_kpd];
//printf("%c\n", tmp_kpd);
if ((tmp_kpd >= '0') && (tmp_kpd <= '9')) {
    if (id_lcd_buff < 16) {
        lcd_buff[id_lcd_buff++] = tmp_kpd;
        if (is_valid) {
            //open key door
            gpioServo(GPIO_SERVO_OUT, 1500);
            //exit_main_loop = 1;
            lcd_printf(&LCD_DEV, 1, "%-16s", "OK");
        } else {
            lcd_printf(&LCD_DEV, 1, "%-16s", "INVALID");
            id_lcd_buff = 0;
            memset(lcd_buff, 0, sizeof (lcd_buff));
        }
    }

    printf("Verification result %s\n", is_valid ? "OK" : "INVALID");

    time_sleep(2.0);
    lcd_printf(&LCD_DEV, 1, "%-16s", " ");
}

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        break;
    }/* clear */
    else if (tmp_kpd == 'C') {
        id_lcd_buff = 0;
        memset(lcd_buff, 0, sizeof (lcd_buff));
        lcd_printf(&LCD_DEV, 1, "%-16s", " ");
    }/* escape */
    else if ((tmp_kpd == '*') || (tmp_kpd == 'D')) {
        printf("Validation aborted\n");
        exit_main_loop = 1;
        gpioServo(GPIO_SERVO_OUT, 800);
        break;
    }/* others */
    else {
//sent email on max retry
        if (i >= 3) {
            printf("Maximum retry reach, send warning notification...\n");
            // kirim email
            //system();
            system("curl -i -F 'filename=frame.jpg' -F 'file=@/dev/shm/frame.jpg'
http://dickiherlambang.esy.es/uploadPhotonew.php");

        }

        lcd_clear(&LCD_DEV);
        lcd_printf(&LCD_DEV, 0, "SYSTEM READY");
    }CV_LOAD_IMAGE_GRAYSCALE));

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        if ((cam_face_detector.face().height >= 100) &&
(cam_face_detector.face().width >= 100)) {
            face_frame = image_frame(cam_face_detector.face());
            imwrite(cv::format("%s%d_%s", dirname.c_str(), dtf,
basename(listfiles[i].c_str())), face_frame);

            printf("POS = %03d,%03d [%03d,%03d]\n",
cam_face_detector.facePosition().x, cam_face_detector.facePosition().y,
cam_face_detector.face().width, cam_face_detector.face().height);
        }

    }

    return EXIT_SUCCESS;
}

/* init pigpio */
if (gpioInitialise() < 0) {
    printf("GPIO Init failed\n");
} else {
    printf("GPIO Init OK\n");

    if (gpioServo(GPIO_SERVO_OUT, 800) == 0) {
        printf("Servo OK\n");
    } else {
        printf("Servo failed\n");
    }
}
}

```

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/* init lcd */
if (lcd_initialize(&LCD_I2C_HDL, &LCD_DEV)) {
    printf("Init lcd ok\n");
    //    lcd_print(&LCD_DEV, "SYSTEM READY", 12, 0);
    lcd_printf(&LCD_DEV, 0, "SYSTEM READY");
} else {
    printf("Init lcd failed\n");
}

/* init face recognizer */
/* read training set images */
read_training_set_folder(argv[2], training_set, training_labels);
/* main loop */
while (s_signal_received == 0) {
    //get frame
    cam_face_detector >> cam_frame;

    //write face frame to /dev/shm
    face_img = cam_face_detector.getFaceFrame(cam_frame);
    imwrite("/dev/shm/facex.jpg", face_img);

    //write cam frame to /dev/shm
    imwrite("/dev/shm/frame.jpg", cam_frame);

    //save to mjpg stream
    //    VideoWriter mjpg_stream("/dev/shm/stream.mjpeg", CV_FOURCC('M',
    'J', 'P', 'G'), 5, Size(320, 240));
    //    if (mjpg_stream.isOpened()) {
    //        printf("Write mjpg stream\n");

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//      mjpg_stream.write(cam_frame);
//    } else {
//      printf("Fail init mjpg stream\n");
//    }
//    if (mjpg_stream.isOpened()) {
//      mjpg_stream.write(cam_frame);
//    }

//print to console
//check for face with height and width >= 100
if ((cam_face_detector.face().width >= 150) &&
(cam_face_detector.face().height >= 150)) {
    printf("Got valid face size\nTry to recognize...\n");

    //recognize it
    if (pr.recognize(face_img, face_confidence, face_predicted_label) != -1) {
        printf("Got match for label %d with confidence %f\n",
face_predicted_label, face_confidence);

        //different face?
        if (face_predicted_label != face_previous_predicted_label) {
            face_previous_predicted_label = face_predicted_label;

            //thresholding confidence level
            if (face_confidence <= 150) {
                /* display to lcd */
                lcd_printf(&LCD_DEV, 0, "%-16s", "ID :");
                lcd_printf(&LCD_DEV, 1, "%-16d", face_predicted_label);
                time_sleep(2.0);
            }
        }
    }
}

```

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        /* verify password */
        verify_password_uid_process(face_predicted_label);
        //break;
        //cam_face_detector = new
VideoFaceDetector(CASCADE_FILEX,cap);
        //cam_face_detector(CASCADE_FILEX,cap);
        //VideoFaceDetector cam_face_detector(CASCADE_FILEX, cap);
    }
}
}
}else{
    face_previous_predicted_label=0;
}
}

/* cleaning */
printf("Close program...\n");
cap.release();
gpioTerminate();
return EXIT_SUCCESS;
}
```