

LAMPIRAN

MainForm.cs

```
using System;
using System.Collections.Generic;
using System.ComponentModel;
using System.Data;
using System.Drawing;
using System.Linq;
using System.Text;
using System.Windows.Forms;
using System.IO.Ports;
using Emgu.CV.UI;
using Emgu.CV;
using Emgu.CV.Structure;
using Emgu.CV.CvEnum;

namespace Face_Recognition
{
    public partial class MainForm : Form
    {
        private SerialPort myport;
        #region variables
        Image<Bgr, Byte> currentFrame; //display image dari webcam
        Image<Gray, byte> result, TrainedFace = null; //used to store the
result image and trained face
        Image<Gray, byte> gray_frame = null; //grayscale current image
acquired from webcam for processing

        Capture grabber; //This is our capture variable

        public CascadeClassifier Face = null;
        MCvFont font; //Our font for writing within the frame

        int NumLabels;

        //Classifier with default training location
        ClassifierTrain Eigen_Recog = new ClassifierTrain();

        #endregion

        public MainForm()
        {
            InitializeComponent();
            init();
        }
        //membuka data training dr data sebelumnya
        private void init()
        {
            myport = new SerialPort();
            myport.BaudRate = 9600;
            myport.PortName = "COM4";
            myport.Open();
        }
    }
}
```

```

        facesDetected[i].Y += (int)(facesDetected[i].Width
* 0.14);
        facesDetected[i].Height -=
(int)(facesDetected[i].Height * 0.1);
        facesDetected[i].Width -=
(int)(facesDetected[i].Width * 0.15);

        result =
currentFrame.Copy(facesDetected[i]).Convert<Gray, byte>().Resize(100, 100,
Emgu.CV.CvEnum.INTER.CV_INTER_CUBIC);
        result._EqualizeHist();
        //draw the face detected in the 0th (gray) channel
with blue color
        currentFrame.Draw(facesDetected[i], new
Bgr(Color.Red), 2);

        if (Eigen_Recog.IsTrained)
        {
            string name = Eigen_Recog.Recognise(result);
            int match_value =
(int)Eigen_Recog.Get_Eigen_Distance;

            //Draw the label for each face detected and
recognized
            currentFrame.Draw(name + " ", ref font, new
Point(facesDetected[i].X - 2, facesDetected[i].Y - 2), new
Bgr(Color.LightGreen));
            label4.Text = name;

            if (name == "harif")
                myport.WriteLine("A");

            if (name == "helen")
                myport.WriteLine("A");

            if (name == "sinar")
                myport.WriteLine("A");

            if (name == "noone")
                myport.WriteLine("B");
        }

    }
    catch
    {
    }
});
image_PICBX.Image = currentFrame.ToBitmap();

```

```

    }
}

//ADD Picture box and label to a panel for each face
int faces_count = 0;
int faces_panel_Y = 0;
int faces_panel_X = 0;
void if_label()
{
    label4.Text = "sinar";
    myport.WriteLine("A");
}

void Clear_label4()
{
    label4.Text = " ";
}

void Clear_Faces_Found()
{
    this.Faces_Found_Panel.Controls.Clear();
    faces_count = 0;
    faces_panel_Y = 0;
    faces_panel_X = 0;
}

void ADD_Face_Found(Image<Gray, Byte> img_found, string
name_person, int match_value)
{
    PictureBox PI = new PictureBox();
    PI.Location = new Point(faces_panel_X, faces_panel_Y);
    PI.Height = 80;
    PI.Width = 80;
    PI.SizeMode = PictureBoxSizeMode.StretchImage;
    PI.Image = img_found.ToBitmap();
    Label LB = new Label( );
    LB.Text = name_person + " " + match_value.ToString();

    LB.Location = new Point(faces_panel_X, faces_panel_Y + 80);
    //LB.Width = 80;
    LB.Height = 15;

    this.Faces_Found_Panel.Controls.Add(PI);
    this.Faces_Found_Panel.Controls.Add(LB);
    faces_count++;
    if (faces_count == 2)
    {
        faces_panel_X = 0;
        faces_panel_Y += 100;
        faces_count = 0;
    }
    else faces_panel_X += 85;

    if (Faces_Found_Panel.Controls.Count > 10)

```

```

        {
            Clear_Faces_Found();
        }
    }

    //Menu Opeartions
    private void exitToolStripMenuItem_Click(object sender, EventArgs
e)
    {
        this.Dispose();
    }

    //Unknow Eigen face calibration
    private void Eigne_threshold_txtbxChanged(object sender, EventArgs
e)
    {
        try
        {
            Eigen_Recog.Set_Eigen_Threshold =
Math.Abs(Convert.ToInt32(Eigne_threshold_txtbx.Text));
            message_bar.Text = "Eigen Threshold Set";
        }
        catch
        {
            message_bar.Text = "Error in Threshold input please use
int";
        }
    }

    private void MainForm_Load(object sender, EventArgs e)
    {
    }

    private void Faces_Found_Panel_Paint(object sender, PaintEventArgs
e)
    {
    }

    private void image_PICBX_Click(object sender, EventArgs e)
    {
    }

    }
}

```

TrainingForm.cs

```

using System;
using System.Collections.Generic;
using System.ComponentModel;
using System.Data;

```

```

using System.Drawing;
using System.Linq;
using System.Text;
using System.Windows.Forms;

using Emgu.CV.UI;
using Emgu.CV;
using Emgu.CV.Structure;
using Emgu.CV.CvEnum;

using System.IO;
using System.Drawing.Imaging;
using System.Xml;
using System.Threading;

namespace Face_Recognition
{
    public partial class TrainingForm : Form
    {
        #region Variables
        //Camera specific
        Capture grabber;

        //Images for finding face
        Image<Bgr, Byte> currentFrame;
        Image<Gray, byte> result = null;
        Image<Gray, byte> gray_frame = null;

        //Classifier
        CascadeClassifier Face;

        //For aquiring 10 images in a row
        List<Image<Gray, byte>> resultImages = new List<Image<Gray,
byte>>();
        int results_list_pos = 0;
        int num_faces_to_aquire = 10;
        bool RECORD = false;

        //Saving Jpg
        List<Image<Gray, byte>> ImagestoWrite = new List<Image<Gray,
byte>>();
        EncoderParameters ENC_Parameters = new EncoderParameters(1);
        EncoderParameter ENC = new
EncoderParameter(System.Drawing.Imaging.Encoder.Quality, 100);
        ImageCodecInfo Image_Encoder_JPG;

        //Saving XAML Data file
        List<string> NamestoWrite = new List<string>();
        List<string> NamesforFile = new List<string>();
        XmlDocument docu = new XmlDocument();

        //Variables
        MainForm Parent;
        #endregion

        public TrainingForm(MainForm parent)

```

```

    {
        InitializeComponent();
        Parent = parent;
        Face = new CascadeClassifier(Application.StartupPath +
"/Cascades/haarcascade_frontalface_default.xml");
        ENC_Parameters.Param[0] = ENC;
        Image_Encoder_JPG = GetEncoder(ImageFormat.Jpeg);
        initialise_capture();
    }

    private void Training_Form_FormClosing(object sender,
FormClosingEventArgs e)
    {
        stop_capture();
        Parent.retrain();
        Parent.initialise_capture();
    }

    //Camera Start Stop
    public void initialise_capture()
    {
        grabber = new Capture();
        grabber.QueryFrame();
        //Initialize the FrameGrabber event
        Application.Idle += new EventHandler(FrameGrabber);
    }
    private void stop_capture()
    {
        Application.Idle -= new EventHandler(FrameGrabber);
        if (grabber != null)
        {
            grabber.Dispose();
        }
        //Initialize the FrameGrabber event
    }

    //Process Frame
    void FrameGrabber(object sender, EventArgs e)
    {
        //Get the current frame form capture device
        currentFrame = grabber.QueryFrame().Resize(320, 240,
Emgu.CV.CvEnum.INTER.CV_INTER_CUBIC);

        //Convert it to Grayscale
        if (currentFrame != null)
        {
            gray_frame = currentFrame.Convert<Gray, Byte>();

            //Face Detector
            //MCvAvgComp[][] facesDetected =
gray_frame.DetectHaarCascade(Face, 1.2, 10,
Emgu.CV.CvEnum.HAAR_DETECTION_TYPE.DO_CANNY_PRUNING, new Size(20, 20));
//old method
            Rectangle[] facesDetected =
Face.DetectMultiScale(gray_frame, 1.2, 10, new Size(50, 50), Size.Empty);

            //Action for each element detected

```

```

        for(int i = 0; i < facesDetected.Length; i++)// (Rectangle
face_found in facesDetected)
        {
            //This will focus in on the face from the haar results
its not perfect but it will remove a majoriy
            //of the background noise

            facesDetected[i].X += (int)(facesDetected[i].Height *
0.1);
            facesDetected[i].Y += (int)(facesDetected[i].Width *
0.14);
            facesDetected[i].Height -=
(int)(facesDetected[i].Height * 0.1);
            facesDetected[i].Width -= (int)(facesDetected[i].Width
* 0.15);

            result =
currentFrame.Copy(facesDetected[i]).Convert<Gray, byte>().Resize(100, 100,
Emgu.CV.CvEnum.INTER.CV_INTER_CUBIC);
            // result._EqualizeHist();
            face_PICBX.Image = result.ToBitmap();
            //draw the face detected in the 0th (gray) channel with
blue color
            currentFrame.Draw(facesDetected[i], new Bgr(Color.Red),
2);
        }
        if (RECORD && facesDetected.Length > 0 &&
resultImages.Count < num_faces_to_acquire)
        {
            resultImages.Add(result);
            count_lbl.Text = "Count: " +
resultImages.Count.ToString();
            if (resultImages.Count == num_faces_to_acquire)
            {
                ADD_BTN.Enabled = true;
                NEXT_BTN.Visible = true;
                PREV_btn.Visible = true;
                count_lbl.Visible = false;
                Single_btn.Visible = true;
                ADD_ALL.Visible = true;
                RECORD = false;
                Application.Idle -= new EventHandler(FrameGrabber);
            }
        }

        image_PICBX.Image = currentFrame.ToBitmap();
    }
}

//Saving The Data
private bool save_training_data(Image face_data)
{
    try
    {
        Random rand = new Random();
        bool file_create = true;
    }
}

```



```

        string facename = "face_" + NAME_PERSON.Text + "_" +
rand.Next().ToString() + ".jpg";
        while (file_create)
        {
            if (!File.Exists(Application.StartupPath +
"/TrainedFaces/" + facename))
            {
                file_create = false;
            }
            else
            {
                facename = "face_" + NAME_PERSON.Text + "_" +
rand.Next().ToString() + ".jpg";
            }
        }

        if(Directory.Exists(Application.StartupPath +
"/TrainedFaces/"))
        {
            face_data.Save(Application.StartupPath +
"/TrainedFaces/" + facename, ImageFormat.Jpeg);
        }
        else
        {
            Directory.CreateDirectory(Application.StartupPath +
"/TrainedFaces/");
            face_data.Save(Application.StartupPath +
"/TrainedFaces/" + facename, ImageFormat.Jpeg);
        }
        if (File.Exists(Application.StartupPath +
"/TrainedFaces/TrainedLabels.xml"))
        {
            //File.AppendAllText(Application.StartupPath +
"/TrainedFaces/TrainedLabels.txt", NAME_PERSON.Text + "\n\r");
            bool loading = true;
            while (loading)
            {
                try
                {
                    docu.Load(Application.StartupPath +
"/TrainedFaces/TrainedLabels.xml");
                    loading = false;
                }
                catch
                {
                    docu = null;
                    docu = new XmlDocument();
                    Thread.Sleep(10);
                }
            }

            //Get the root element
            XmlElement root = docu.DocumentElement;

            XmlElement face_D = docu.CreateElement("FACE");

```

```

XmlElement name_D = docu.CreateElement("NAME");
XmlElement file_D = docu.CreateElement("FILE");

//Add the values for each nodes
//name.Value = textBoxName.Text;
//age.InnerText = textBoxAge.Text;
//gender.InnerText = textBoxGender.Text;
name_D.InnerText = NAME_PERSON.Text;
file_D.InnerText = facename;

//Construct the Person element
//person.Attributes.Append(name);
face_D.AppendChild(name_D);
face_D.AppendChild(file_D);

//Add the New person element to the end of the root
element
root.AppendChild(face_D);

//Save the document
docu.Save(Application.StartupPath +
"/TrainedFaces/TrainedLabels.xml");
//XmlElement child_element =
docu.CreateElement("FACE");
//docu.AppendChild(child_element);
//docu.Save("TrainedLabels.xml");
}
else
{
    FileStream FS_Face =
File.OpenWrite(Application.StartupPath +
"/TrainedFaces/TrainedLabels.xml");
using (XmlWriter writer = XmlWriter.Create(FS_Face))
{
    writer.WriteStartDocument();
    writer.WriteStartElement("Faces_For_Training");

    writer.WriteStartElement("FACE");
    writer.WriteElementString("NAME",
NAME_PERSON.Text);

    writer.WriteElementString("FILE", facename);
    writer.WriteEndElement();

    writer.WriteEndElement();
    writer.WriteEndDocument();
}
FS_Face.Close();
}

return true;
}
catch (Exception ex)
{
return false;
}
}

```

```

private ImageCodecInfo GetEncoder(ImageFormat format)
{
    ImageCodecInfo[] codecs = ImageCodecInfo.GetImageDecoders();
    foreach (ImageCodecInfo codec in codecs)
    {
        if (codec.FormatID == format.Guid)
        {
            return codec;
        }
    }
    return null;
}

//Delete all the old training data by simply deleting the folder
private void Delete_Data_BTN_Click(object sender, EventArgs e)
{
    if (Directory.Exists(Application.StartupPath +
"/TrainedFaces/"))
    {
        Directory.Delete(Application.StartupPath +
"/TrainedFaces/", true);
        Directory.CreateDirectory(Application.StartupPath +
"/TrainedFaces/");
    }
}

//Add the image to training data
private void ADD_BTN_Click(object sender, EventArgs e)
{
    if (resultImages.Count == num_faces_to_acquire)
    {
        if (!save_training_data(face_PICBX.Image))
        MessageBox.Show("Error", "Error in saving file info. Training data not
saved", MessageBoxButtons.OK, MessageBoxIcon.Error);
    }
    else
    {
        stop_capture();
        if (!save_training_data(face_PICBX.Image))
        MessageBox.Show("Error", "Error in saving file info. Training data not
saved", MessageBoxButtons.OK, MessageBoxIcon.Error);
        initialise_capture();
    }
}

private void Single_btn_Click(object sender, EventArgs e)
{
    RECORD = false;
    resultImages.Clear();
    NEXT_BTN.Visible = false;
    PREV_btn.Visible = false;
    Application.Idle += new EventHandler(FrameGrabber);
    Single_btn.Visible = false;
    count_lbl.Text = "Count: 0";
    count_lbl.Visible = true;
}

//Get 10 image to train
private void RECORD_BTN_Click(object sender, EventArgs e)

```

```

{
    if (NAME_PERSON.Text != "")
    {
        if (RECORD)
        {
            RECORD = false;
        }
        else
        {
            if (resultImages.Count == 10)
            {
                resultImages.Clear();
                Application.Idle += new EventHandler(FrameGrabber);
            }
            RECORD = true;
            ADD_BTN.Enabled = false;
        }
    }
    else
    {
        MessageBox.Show("Write Person Name First!! ");
    }
}

private void NEXT_BTN_Click(object sender, EventArgs e)
{
    if (results_list_pos < resultImages.Count - 1)
    {
        face_PICBX.Image =
resultImages[results_list_pos].ToBitmap();
        results_list_pos++;
        PREV_btn.Enabled = true;
    }
    else
    {
        NEXT_BTN.Enabled = false;
    }
}

private void PREV_btn_Click(object sender, EventArgs e)
{
    if (results_list_pos > 0)
    {
        results_list_pos--;
        face_PICBX.Image =
resultImages[results_list_pos].ToBitmap();
        NEXT_BTN.Enabled = true;
    }
    else
    {
        PREV_btn.Enabled = false;
    }
}

private void ADD_ALL_Click(object sender, EventArgs e)
{
    for(int i = 0; i<resultImages.Count;i++)
    {
        face_PICBX.Image = resultImages[i].ToBitmap();
    }
}

```

```

        if (!save_training_data(face_PICBX.Image))
    MessageBox.Show("Error", "Error in saving file info. Training data not
    saved", MessageBoxButtons.OK, MessageBoxIcon.Error);
        Thread.Sleep(100);
    }
    ADD_ALL.Visible = false;
    //restart single face detection
    Single_btn_Click(null, null);
}

private void TrainingForm_Load(object sender, EventArgs e)
{

}

private void image_PICBX_Click(object sender, EventArgs e)
{

}

}
}

```

Servo

//control servo motor with serial monitering window - by ujash patel

//for more go to www.uu-machinetool.blogspot.com

```
#include <Servo.h>
```

```
Servo myservo; // create servo object to control a servo
```

```
// a maximum of eight servo objects can be created
```

```
int pos = 0;
```

```
int servodata;
```

```
void setup()
```

```
{
```

```
Serial.begin(9600);
```

```

Serial.println("Wisuda");

Serial.println("Sinar Monika ");

Serial.println("0613 4035 1630");

Serial.println("8 TEB");

myservo.attach(9);

}

void loop()
{
  if (Serial.available() > 0)
  {
    servodata = Serial.read();

    if(servodata == 'A') // Single Quote! This is a character.
    {
      Serial.println("speed 1 is selected");
      Serial.println("DELAY 15MS");

      // in steps of 1 degAAree
      // goes from 0 degrees to 180 degrees
      // goes from 0 degrees to 180 degrees
      // in steps of 1 degree
      // in steps of 1 degree

      myservo.write(0); // tell servo to go to position in variable 'pos'
      delay(15); // waits 15ms for the servo to reach the position
    }
  }
}

```

```

        // waits 15ms for the servo to reach the position
    }

    // waits 15ms for the servo to reach the position

}

if(servodata== 'B')
{
    Serial.println("No speed");

    Serial.println(" Stop ");

    // goes from 0 degrees to 180 degrees // in steps of 1
    degree

        // in steps of 1 degAAre

    myservo.write(40);

    delay(15);

}

}

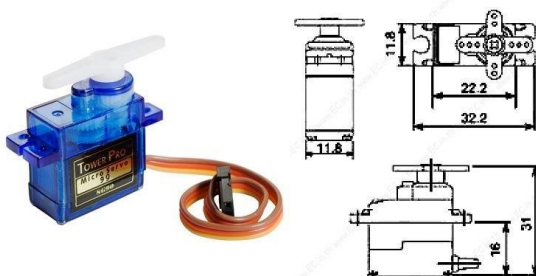
```

Datasheet

Servo

SG90

9 g Micro Servo



Tiny and lightweight with high output power. Servo can rotate approximately 180 degrees (90 in each direction), and works just like the standard kinds but *SMALLER*. You can use any servo code, hardware or library to control these servos. Good for beginners who want to make stuff move without building a motor controller with feedback & gear box, especially since it will fit in small places. It comes with a 3 horns (arms) and hardware.

Specifications

- Weight: 9 g
- Dimension: 22.2 x 11.8 x 31 mm approx.
- Stall torque: 1.8 kgf·cm
- Operating speed: 0.1 s/60 degree
- Operating voltage: 4.8 V (~5V)
- Dead band width: 10 μ s
- Temperature range: 0 °C – 55 °

Position "0" (1.5 ms pulse) is middle. 90° (~2 ms pulse) is all the way to the right, "-90" (~1 ms pulse) is all the way to the left.

